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(54)Method for determining the attenuation of a PCM signal over a digital channel

(57)A method of determining digital channel attenuation; comprising the steps of: receiving a known training sequence of PCM codes, which PCM codes are subjected to the attenuation within the digital channel; quantizing the received known training sequence of PCM codes according to a predetermined thresholding procedure; identifying identical PCM codes created as a result of the thresholding procedure; and, determining the attenuation of the digital channel based upon the identification of identical PCM codes. A method is also disclosed for determining a digital channel PCM code transformation comprising receiving a known training sequence of PCM codes, which PCM codes are subjected to the PCM code transformation within the digital channel, quantizing the received known training sequence of PCM codes according to a predetermined thresholding procedure, and determining the transformation of transmitted codes to those received . A method is also disclosed for improved echo cancellation in a communications network having an analog and a digital modem, comprising saving codes transmitted from the digital modem to the analog modem for echo cancellation, transforming, by a mapping table, codes transmitted from said digital modem to codes received by the analog modem, and, using the received codes as a reference signal for cancellation of echo. A method of improved spectral shaping using a transmit shaping transfer function in a communications network having an analog and a digital modem, comprising, transforming, by a mapping table, codes transmitted from the digital modem to codes received by the analog modem,

using the received codes for transformation to their linear value equivalent representations, and, applying the linear value representations to the transmit shaping transfer function.

Description

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Field of the Invention

This invention pertains generally to modem technology, more specifically to PCM modem technology, and more specifically, to a method for the discovery of the digital attenuation from a set of received PCM samples corresponding to a known set of transmit PCM samples.

Background of the Invention

This invention provides a method for the discovery of the digital attenuation from set of received pulse code modulation (PCM) samples corresponding to a known set of transmit PCM samples. The principal feature set used is the knowledge of which received PCM codes have become indistinguishable (i.e., are identical) as a result of the attenuation mapping. An alternative but equivalent feature set would be use of the absent received PCM codes.

The question of digital attenuation PAD mapping has been raised at recent meetings of the Telephone Industry of America (TIA) PCM Modem Ad-hoc Committee. Many participants have been hoping for a single industry standard mapping solution. We provide a solution, which will allow PCM modems to function properly throughout the entire telephone network including with private telephone equipment (PBX's and key systems).

20 <u>TIA 464A</u>

TIA 464A is the industry standard plan for private telephone equipment. Among other recommendations, this specification provides the recommended losses between T1 lines and other devices. If a PBX is designed according to the loss-plan specification as outlined in sections 4.8.4 and 4.8.5 of 464A, then it should not be necessary to attenuate the PCM on incoming T1 lines for on-premise (ONS) connections, since the recommended 3-dB loss is typically implemented in the analog circuitry of the ONS codec.

However, Inter-Tel's experience with customers using T1 lines suggests that the recommended 3-dB of insertion loss is inadequate and that T1 attenuation pads are indeed necessary. While the standard -3 and -6 dB pads are usually adequate, Inter-Tel has provided a wider-range of insertion loss as options for PBX customers. Inter-Tel has implemented digital gain control on its T1 line cards using two different methods:

- · ROM-based mapping
- DSP-based algorithm

35 ROM Based Mapping

Inter-Tel first implemented attention pads via an EPROM circuit, which used the incoming PCM code as 8 bits of an address and additional address bits selecting the attenuation in 1 dB increments. The output of the EPROM was the attenuated digital PCM code. In this implementation, the attenuation range covered from 0 dB to -12 dB in 1 dB steps.

Experience with customers shows that 0 to -6 dB seems to be the most-often used range of T1 pad values. Taking into account the fixed 3-dB of loss included with our ONS card, the net insertion loss for to Digital CO connection is then -3dB to -9dB, which mimics well the typical net losses experienced by customers on ONS to Analog CO connections.

All attenuation tables in the EPROM preserved the LSB of the PCM to preserve the state of the Robbed Bit Signaling (RBS), if present. However, the preservation of the LSB is unnecessary if no RBS information passes through the ROM-based gain control circuitry.

The ROM-based look-up tables were generated by a custom C program using the following algorithm:

- 1. Expand incoming 8-bit,u-Law PCM to corresponding 14-bit, signed integer linear value, x
- 2. Calculate output, y, based on equation: y=INT [x*10 (gain/20))+0.500]
- 3. Compress y back into its corresponding 8-bit u-Law value using G.711 decision values.

In addition to performing u-Law to u-Law digital gain control (DGC) through look-up tables, the EPROM also performs DGC through look-up tables for the following compression schemes:

- 55 u-Law-to-A-law
 - A-law-to-u-Law
 - A-law-to-A-law

DSP Based Mapping

With the advent of DSP's, for their greater flexibility, the latest implementation uses the Analog Devices 21xx fixed point family of processors. The PCM codes are converted to/from linear values by the ADSP-21xx internal companing hardware. Inter-Tel's algorithm normalizes the linear value before applying the attenuation multiplier. The attenuation is selectable as a linear 1.15 fractional multiplier. The user interface selects the attenuation in fixed, 1-dB steps over a similar range as the previous implementation. The user configured dB attenuation is converted to the linear fractional multiplier by an algorithm. Moreover, the instructions in the Analog Devices DSP can use unbiased rounding, truncation and in newer family members, biased rounding. Inter-Tel's implementation uses the unbiased rounding option (RND) during the MAC instruction. This flexibility in rounding and truncation obviously can have a substantial effect on the actual attenuation mapping, with the additional caveat of having potentially different mappings for positive and negative PCM codes.

Detailed Description of the Preferred Embodiment

Detection of the Feature Set

After a receiver's equalizer has been trained, a known transmit sequence of PCM codes can be sent and received using either all or a useful subset of PCM codes. (This sequence may need to be sent multiple times to cover all 6 or 12 bit positions in a robbed bit signaling system.) The receiver can save the linear values for each received PCM code. From the known step size between adjacent PCM codes, the receiver can determine those PCM samples that it received which are indistinguishable. The indistinguishable samples arise from two transmit PCM codes which when scaled by the same attenuation and quantized according to a thresholding procedure create identical PCM codes.

An example taken from the attached attenuation table (pages A1-A2) which shows the attenuation for each uLaw PCM code when it is transformed by shifting from 1 to 26 codes numerically.

Example:

Transmit	ted	Received shifted by 1 PCM code					
uLaw	Linear	uLaw	Threshold	Attenuation	dB		
129	7775	129	7647	0.983537	-0.14419		
128	8031		7903	0.984062	-0.13955		

Processing of Indistinguishable PCM Codes

The processing of the feature set relies on knowledge of the coding law (uLaw or Alaw) used. In practice, it is necessary to consider the preciseness of the numerics used in the attenuation process. Suggestions for accommodating implementation deviations is discussed in a later section. The attached C language source code provided as part of this application (pages B1- B21) implements a demonstration of the identification procedure indistinguishably codes. The basic algorithm is the following:

- 1. For each indistinguishable PCM code received, the original pair of transmitted PCM codes can be determined since the PCM codes are sent in a known training sequence. A set of indistinguishable transmitted PCM code pairs are determined from this training sequence.
- 2. For the first indistinguishable PCM code pair, determine the minimum attenuation required for the larger transmitted PCM code to be attenuated to a number of successive lower PCM codes. (A set of 30 successive lower PCM codes would be sufficient to cover an attenuation range of approximately 11 dB.) Then determine the maximum attenuation permitted for the smaller transmitted PCM code to be attenuated to the same successive lower PCM codes. (Minimum attenuation is numerically closer to one, i.e., a lesser attenuation, while a maximum attenuation is a greater attenuation.) If the maximum attenuation is a smaller attenuation than the minimum attenuation, discard the attenuation range as it represents a missing code rather than an indistinguishable code. The minimum and maximum attenuations for each successive lower PCM code forms an initial set of candidate attenuation ranges.
- 3. For each successive indistinguishable transmit PCM code pair, another set of possible attenuation ranges is. determined using the procedure as described in Step 2. Each element of the candidate attenuation range set cre-

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ated in Step 2 is searched for either full or partial overlap with any element of the possible attenuation range set. (In case of partial overlap, the attenuation range in the candidate set can be reduced for refined attenuation accuracy.) In case of no overlap, the candidate attenuation range should be discarded. The discard occurs because two different indistinguishable codes must arise from the same linear transformation.

4. Step 3 is repeated for successive pairs of indistinguishable transmit PCM code pairs until either a) the set of candidate attenuation ranges is reduced to a single range or b) all the pairs of indistinguishable transmit PCM code pairs have been processed.

In the first case, the actual attenuation is bounded by the single remaining attenuation range. We can say it is the detected attenuation can be the average of the high and low attenuations. Alternatively, if the history of each overlapping attenuation range is maintained (or regenerated) a probabilistic approach of determining a weighted median value for determining the detected attenuation can be implemented.

For the second case where the attenuation appears to remains non-unique, the set of candidate attenuation ranges can be used to determine multiple sets of indistinguishable PCM code pairs can be determined for each candidate attenuation. The generated sets of indistinguishable PCM code pairs can then be matched with the original received set. The generated set using the correct attenuation should match nearly identically if not identically. The sets corresponding to incorrect potential attenuations would generate significant number of additional pairs of indistinguishable PCM code pairs or have missing indistinguishable PCM code pairs. Thus the correct detected attenuation can still be determined using this procedure. (Multiple candidate attenuations appear to arise from attenuations of 6 dB or greater combined with the decreasing step sizes used in with uLaw or Alaw companding.)

Processing of Missing PCM Codes

The procedure described above for using indistinguishable PCM codes to determine the attenuation can be adapted to operate with missing received PCM codes. The transmitted PCM codes corresponding each of the received PCM codes around the missing PCM code can be determined. Follow the same algorithm except that the minimum and maximum attenuations are exchanged in the algorithms. In other words, the larger transmitted PCM code produces the maximum attenuation and the smaller transmitted PCM code produces the minimum attenuation. With this adaptation, the algorithm described remains essentially the same.

Example:

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Transmi	tted	Recieved shifted by I PCM code					
uLaw	Linear	uLaw	Threshold	Attenuation	dB		
144	3999	144	3935	0.983996	-0.14013		
143	4191		4063	0.969458	-0.26942		

Other Variations

For robustness with real signals corrupted by noise, it may be desirable to allow a certain number of pairs of indistinguishable PCM codes not to match a candidate range. An alternative to simply dropping a candidate attenuation range would be to use a probabilistic greatest likelihood model for selection of the detected attenuation.

Furthermore, given that implementers of digital attenuation pads may understand and implement the mapping process slightly differently (i.e., use of G.711 threshold values or average between PCM codes) and allow various inaccuracies in the numerical operations (numeric representation, rounding, truncation, etc.), each candidate attenuation range may need to be broadened to make overlap again more likely. The broadening can be by a fixed value or a relative amount about the attenuation computed. The previous suggestion of discarding a certain number of pairs of indistinguishable PCM codes also addresses this problem as very few pairs are likely to be affected by these numerical inaccuracies.

As for digital attenuation pads that pass through the robbed bit signaling (RBS) information, the algorithms presented can also be applied except that `the indistinguishable transmit PCM code pairs will be separated by one code and a second indistinguishable transmit PCM code pair will adjacent. The candidate attenuation ranges become bigger, but still can be matched by the procedures presented in this invention.

The procedures described in this invention suggest a robust manner to identify the digital channel attenuation

though the use of received PCM codes corresponding to a known transmit PCM code sequence. The use of such an algorithm would be necessary when the FCC permits the channel power to be increased in compensation for the systematic digital attenuations.

We further suggest that knowledge of the exact received PCM code set may be preferred by both the analog and digital PCM modems. Echo cancellation in the digital PCM modem may operate with incrementally better performance with the knowledge of actual PCM codes presented to the Codec. The receiver's desired spectral shaping can be more precisely honored by having the transmitter use the knowledge of the actual PCM codes presented to the Codec in the shaping function implementation, then reversely mapping the PCM code after shaping to the transmit PCM code to be sent.

The exclusive use of pre-identified attenuation table mappings would make the PCM modern technology incapable of operating with existing private telephone equipment. It is recommended that the attenuation pad mappings be discovered for each connection.

Claims

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- A method of determining digital channel attenuation, comprising:
 - receiving a known training sequence of PCM codes, which PCM codes are subjected to said attenuation within said digital channel;
 - quantizing said received known training sequence of PCM codes according to a predetermined thresholding procedure;
 - identifying identical PCM codes created as a result of said thresholding procedure; and,
 - determining said attenuation of the digital channel based upon said identification of identical PCM codes.
- 25 2. A method of determining digital channel attenuation, comprising:
 - receiving a known training sequence of PCM codes, which PCM codes are subjected to said attenuation within said digital channel;
 - quantizing said received known training sequence of PCM codes according to a predetermined thresholding procedure;
 - identifying PCM codes omitted as a result of said thresholding procedure; and,
 - determining said attenuation of the digital channel based upon said identification of omitted PCM codes.
 - 3. A method of determining a digital channel PCM code transformation comprising:
 - receiving a known training sequence of PCM codes, which PCM codes are subjected to said PCM code transformation within said digital channel;
 - quantizing said received known training sequence of PCM codes according to a predetermined thresholding procedure; and
 - determining the transformation of transmitted codes to those received.
 - 4. A method of improved echo cancellation in a communication network having an analog and a digital modem, comprising:
 - saving codes transmitted from said digital modem to said analog modem for echo cancellation;
 - transforming, by a mapping table, codes transmitted from said digital modern to codes received by said analog modern; and
 - using said received codes as a reference signal for cancellation of echo.
- 50 S. A method of improved spectral shaping using a transmit shaping transfer function in a communications network having an analog and a digital modem, comprising:
 - transforming, by a mapping table, codes transmitted from said digital modern to codes received by said analog modern:
- using said received codes for transformation to their linear value equivalent representations; and, applying said linear value representations to said transmit shaping transfer function.

by 26

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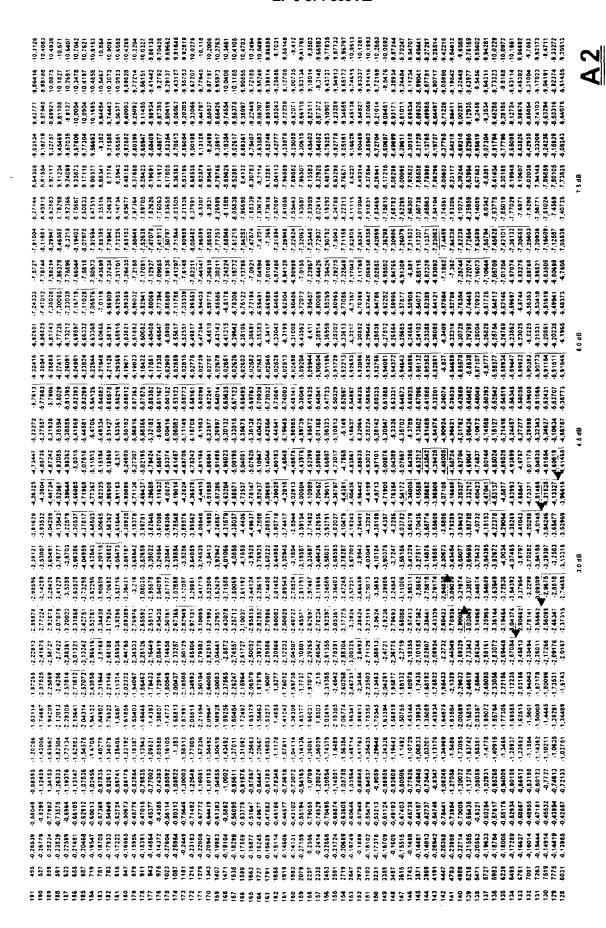
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ULAW LINEAR By 1

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by 16	↑ ↓	-20,3703 -21,8216 -18,2763 -16,1623 -14,7191 -13,8577 -12,8386 -13,8386 -14	-10,4963 -10,2109 -10,2109 -9,9611	6,73643 6,64243 6,76638 6,54468 6,36618	6,19402 -6,05304 -7,82931 -7,8293 -7,72226 -7,53478 -7,48629	7,758813 7,756864 7,756864 7,75641 7,70166 6,84748 6,84748 6,84748 6,67184 6,67186 6,67186 6,67186 6,67186 6,67186 6,67186 6,67186 6,67186 6,67186 6,67186	
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pcmmap.c
           (C) 1997 VoCAL Technologies Ltd.
           ALL RIGHTS RESERVED. PROPRIETARY AND CONFIDENTIAL.
           VoCAL Technologies Ltd.
3032 Scott Blvd.
Santa Clara, CA 95054
           Product
                                С
           Module:
                                          PCM
           This file contains the PCM mapping functions.
           Revision Number:
                                          $Revision$
           Revision Status:
Last Modified
                                          $State$
$Date$
           Identification:
                                          $1d$
           Revision History: $Log$
Revision 1.0 1997/03/01 00:00.00 VD
Initial release of software
   #include "standard.h"
#include "pcm.h"
#include <stdio.h>
 #include <math.h>
 struct law_array_s {
    sint15 code:
    sint15 'inear;
    sint15 other:
    sint15 deselect:
}:
struct law_s {
    float tx_power_db:
    float rx_power_db;
    sint15 count:
        sint15 dmin:
        sint15 indistinguishable;
        sint31 bit_rate,
        struct law_array_s value[128]:
} u_law_u_law_rx:
#define LAW_SELECTED
#define LAW_DESELECTED_MIN
#define LAW_DESELECTED_MAX
#define LAW_DESELECTED_DMIN
#define LAW_DESELECTED_AVOID
#define LAW_DESELECTED_DUPLICATE
#define LAW_DESELECTED_POWER
                                                                        0x0001
0x0002
                                                                        0x0004
                                                              8000x0
                                                              0x0010
                                                              0x0020
#define MAP_FRAME_SIZE
uint48 frame_slot_modulus[MAP_FRAME_SIZE]; uint48 total_symbols_per_frame.
#define USE_4D_TRELLIS
u_law_init (struct law_s *law)
```

```
sint15 idx. pcm;
           law->tx_power_db = 0.0;
law->rx_power_db = 0.0;
law->count = 0;
           law->indistinguishable = 0:
           law->dmin = 0.
           law->bit_rate = 0L;
           for (idx = 0); idx < 128; ++idx) {
                     pcm = 255 - idx:
                    law->value[idx] code = pcm;
law->value[idx].linear = u_law_pcm_decode (pcm);
law->value[idx] other = u_law_pcm_threshold (pcm);
law->value[idx] deselect = LAW_SELECTED;
 #define SELECT_LARGER
                                                  /* appears to work better with standard 3 and 6 dB attenuation */
 u_law_attenuate (struct law_s *law, float attn_db) {
           sint15 idx, pcm;
           float attn:
           attn = db_to_float (-attn_db);
           law->tx_power_db = 0.0;
          law->rx_power_db = 0.0;
law->count = 0;
          law->indistinguishable = 0:
law->dmin = 0;
           law->bit_rate = 0L,
          for (idx = 0; idx < 128, ++idx) {
    pcm = 255 - idx;
                    law->value[idx].other = (sint15) ((float) (u_law_pcm_decode (pcm)) * attn); law->value[idx].code = u_law_pcm_encode (law->value[idx].other); law >value[idx].linear = u_law_pcm_decode (law->value[idx].code); law->value[idx].deselect = LAW_SELECTED;
                    if (idx = 0)
// if (law->value[idx].code == law->value[idx-1].code) {
//#ifdef SELECT_LARGER
                                        law->value[idx-1].deselect = LAW_DESELECTED_DUPLICATE:
//#else
                                        law->value[idx].deselect = LAW DESELECTED DUPLICATE;
//#endif
//
                    }
          }
u_law_range (struct law_s *law, sint15 min, sint15 max)
          sint15 idx;
          for (idx = 0, idx < 128; ++idx) {
                   if (law->value[idx] linear > max) {
    law->value[idx].deselect |= LAW_DESELECTED_MAX;
}
u law dmin (struct law_s *law, sint15 dmin)
```

```
sint15 idx, pcm;
sint15 current;
         current = law->yalue[125].linear;
law->value[127].deselect |= LAW_DESELECTED_AVOID;
law->value[126].deselect |= LAW_DESELECTED_AVOID;
         for (idx = 124; idx >= 0; --idx) {
    if (law->value[idx].linear > (current - dmin)) {
        law->value[idx].deselect |= LAW_DESELECTED_DMIN;
                  }
else {
                           current = law->value[idx].linear;
u_law_discard_indinstinguishable (struct law_s *law)
         sint15 idx;
         for (idx = 1; idx < 125; ++idx) {
    if (law->value[idx].code == law->value[idx-1].code) {
//#ifdef SELECT_LARGER
                           law->value[idx-1].deselect |= LAW_DESELECTED_DUPLICATE;
//#else
                           law->value[idx].deselect |= LAW_DESELECTED_DUPLICATE;
//#endif
else {
                                     law->value[idx].deselect |= LAW_DESELECTED_DUPLICATE;
                  }
}
void
u_law_attenuate_dmin (struct law_s *tx_law, struct law_s *rx_law)
         sint15 idx;
         rx_law->value[127].deselect |= LAW_DESELECTED_AVOID;
rx_law->value[126].deselect |= LAW_DESELECTED_AVOID;
         for (idx = 124; idx >= 0; --idx) {
    if (tx_law->value[idx].deselect & LAW_DESELECTED_DMIN) {
        rx_law->value[idx].deselect |= LAW_DESELECTED_DMIN;
void
u_law_exclude (struct law_s *law)
         sint15 idx, pcm;
         for (idx = 127; idx \geq = 0; --idx) {
                  pcm = 255 - idx;
                  }
u_law_power (struct law_s *law, float max_db)
```

<u>B3</u>

```
{
           sint15 idx, count, dmin, prev;
          float factor, power, max_float;
float tx_power, tx_sum, rx_power, rx_sum;
           factor = pow (10.0, ((3.17 + 3.01244) / 20.0)) / 8159.0;
           count = 0;
          tx_sum = 0.0;
rx_sum = 0.0;
           dmin = 8159:
           prev = -8159;
          max_float = db_to_power (max_db):
for (idx = 0; idx < 128; ++idx) {
    if (law->value[idx].deselect == 0).{
                               rx_power = law->value(idx).linear * factor;
rx_power = rx_power * rx_power;
rx_power = rx_power + rx_sum;
                                tx_power = u_law.value[idx].linear * factor;
tx_power = tx_power * tx_power;
tx_power = tx_power + tx_sum;
                               power = tx_power / (float) (count + 1);
if (power <= max_float) {
    rx_sum = rx_power;
    tx_sum = tx_power;
    count + +;</pre>
                                          if ((law->value[idx].linear - prev) < dmin) {
    dmin = law->value[idx].linear - prev;
                                          prev = law->value[idx].linear;
                                élse {
                                          law->value[idx].deselect = LAW_DESELECTED_POWER;
//printf ("%f %f %d %d\n", power, tx_sum, count, law->value[idx].deselect);
              power = tx_sum / (float) count;
           tx_power = power_to_db (tx_power);
           rx power = rx_sum / (float) count;
           rx_power = power_to_db (rx_power);
           law->tx_power_db = tx_power;
law->rx_power_db = rx_power;
law->count = count;
           law->dmin = dmin;
           return power;
  *************
void
u_law_count_indinstinguishable (struct law_s *law)
           sint15 idx, count;
           count = 0;
           for (idx = 1; idx < 128; ++idx) {
    if (law->value[idx].deselect == LAW_DESELECTED_DUPLICATE) {
                                count++;
                     }
           faw->indistinguishable = count;
}
   ************************
u_law_bit_rate (struct law_s *law)
           float bit_rate_float;
           bit_rate_float = (log10 ((float) law->count * 2.0) / log10(2.0)) * 8000.0; law->bit_rate = (sint31) bit_rate_float;
```

```
return law->bit_rate;
  }
  //#define MAX_SHIFT 20
#define MAX_SHIFT 30
//#define MAX_SHIFT 40
                                       /* covers to -7.08 dB */
/* covers to -11.2 dB */
                                                /* covers to -14 65 dB */
  u_law_detect_attenuation (struct law_s *law)
           sint15 idx, idx1, idx2, idx3, trim; sint15 count;
           float attn_low[MAX_SHIFT], attn_high[MAX_SHIFT];
float a_low[MAX_SHIFT], a_high[MAX_SHIFT];
           float aftn. diff;
           count = 0;
           idx3 = 0;
           for (idx = 128; idx >= MAX_SHIFT; --idx) {
    if (law->value[idx].deselect & LAW_DESELECTED_DUPLICATE) {
                              idx3++
                              if (count == 0) {
                                       for (count = 0; count < MAX_SHIFT: ++count) {
  #ifdef SELECT_LARGER
                                                attn_high[count] = (float) u_law.value[idx-count].other / (float)
  u_law.value[idx+1].linear;
                                                attn_low[count] = (float) u_law.value[idx-count-1].other / (float)
  u_law.value[idx].linear;
 #else
                                                attn_high[count] = (float) u_law.value[idx-count-1].other / (float)
 u_law.value[idx].linear:
                                               attn_low[count] = (float) u_law.value[idx-count-2].other / (float)
 u_law.value[idx-1].linear:
 #endif
                                               printf ("original %d %f %f\n", u_law.value[idx].code,
 attn_high[count], attn_low[count]);
                                      count = MAX SHIFT;
                             }
                             else {
                                      for (idx1 = 0; idx1 < MAX\_SHIFT; ++idx1) {
 #ifdef SELECT_LARGER
                                               a_high[idx1] = (float) u_law.value[idx-idx1].other / (float)
 u_law.value[idx+1].linear;
                                               a_low[idx1] = (float) u_law.value[idx-idx1-1].other / (float)
 u_law.value[idx].linear;
                                               a_high[idx1] = (float) u_law.value[idx-idx1-1].other / (float)
 u_law.value[idx].linear;
                                               a_low[idx1] = (float) u_law.value[idx-idx1-2].other / (float)
 u_law.value[idx-1].linear;
#endif
                                               printf ("generating %d %f %f\n", u_law.value[idx].code.
a_high[idx1], a_low[idx1]);
                                     }
                                     for (idx1 = 0; idx1 < count; ++idx1) {
                                              trim = 1;
for (idx2 = 0; idx2 < MAX_SHIFT; ++idx2) {
    if ((attn_high[idx1] >= a_high[idx2]) && (attn_low[idx1] <=
a_high[idx2])) {
                                                                printf ("reduce high %f %f %f\n",
attn_high[idx1], attn_low[idx1], a_high[idx2]),
                                                                attn_high[idx1] = a_high[idx2]:
                                                       }
if ((attn_high[idx1] >= a_low[idx2]) && (attn_low[idx1] <=
a_low[idx2])) {
                                                                printf ("increase low %f %f %f\n",
attn_high[idx1], attn_low[idx1], a_low[idx2]);
                                                                attn_low[idx1] = a_low[idx2];
                                                                trim = 0:
```

```
if ((attn_high[idx1] <= a_high[idx2]) && (attn_locv[idx1] >
 a_low[idx2])) {
                                                                                                      printf ("hold %% %fin", attn_high[idx1].
 attn_low[idx1]):
                                                                                                      trim = 0;
                                                                         if (attn_high[idx1] < attn_low[idx1]) {</pre>
                                                                        }
if (trim) {
                                                                                       frintf ("trim %f %f\n", attn_high[idx1], attn_tow[idx1]):
for (idx2 = idx1; idx2 < (count - 1); ++idx2) {
    attn_high[idx2] = attn_high[idx2+1];
    attn_low[idx2] = attn_Tow[idx2+1];</pre>
 11
                                                                                        --count:
                                                                                       --idx1:
                                           if (count <= 0) {
    printf ("count break\n"):
 #
                                                           break:
                                            If (idx3 >= 10) break:
 11
              }
if (count > 1) {
    altn = (attn_high[0] + attn_low[0]) / 2.0;
    diff = attn_high[0] - attn_low[0];
    for (idx1 = 1; idx1 < count; ++idx1) {
        if ((attn_high[idx1] - attn_low[idx1]) < diff) {
            attn = (attn_high[idx1] + attn_low[idx1]) / 2.0;
            diff = attn_high[idx1] - attn_low[idx1];
    }
                             printf ("Muplitple potential attenuations detected, resolve by generating and matching\n" "duplicated codes to those observed. Currently choosing largest
 IIv
 //v
range.\n");
               else {
                             attn = (attn_high[0] + attn_low[0]) / 2.0:
               attn = log10 (attn) * 20.0:
//
               printf ("count %d attempts %d range %f %f\n" count, idx3. attn_high[0], attn_low[0]);
11
               printf ("attenuation detected %f\n", attn);
               return attn.
sint15
u_law_map_symbol_set (struct law_s "tx_law, struct law_s "rx_law)
              sint15 idx. count. limit: uint16 mask.
              total_symbols_per_frame.lsw = 1,
total_symbols_per_frame.mid = 0;
total_symbols_per_frame.msw = 0.
              printf("%04x %04x %04x\n", total_symbols_per_frame.msw, total_symbols_per_frame.mid, total_symbols_per_frame.lsw);
              for (idx = 0: idx < MAP_FRAME_SIZE: ++idx) {
    frame_slot_modulus[idx] lsw = total_symbols_per_frame.lsw;
    frame_slot_modulus[idx].mid = total_symbols_per_frame.mid;
    frame_slot_modulus[idx].msw = total_symbols_per_frame.msw;
#ifdef USE_4D_TRELLIS
                            limit = tx_law->count; if (idx & 1) {
                                          limit = limit >> 1;
```

```
#else
                 #endif
                 printf("%04x %04x %04x\n", total_symbols_per_frame.msw, total_symbols_per_frame.mid, total_symbols_per_frame.lsw);
 11
         }
         count = 47;
         mask = 0x8000;

for (idx = 0; idx < 16; ++idx) {

    if (mask & total_symbols_per_frame.msw) {

        return count;
                 --count;
         }
         mask = 0x8000:
         for (idx = 0: idx < 16: ++idx) {
    if (mask & total_symbols_per_frame.mid) {
        return count;
}
                 mask = mask >> 1;
                 --count:
         }
         mask = 0x8000;
for (idx = 0; idx < 16; ++idx) {
    if (mask & total_symbols_per_frame.tsw) {
                         return count:
                 mask = mask >> 1;
                 --count;
         return count;
       ······
print_deselect (sint15 deselect)
        if (deselect & LAW_DESELECTED_MIN) {
    printf ("(Below Min)");
        if (deselect & LAW_DESELECTED_MAX) {
                printf ("(Above Max) "):
        )
        if (deselect & LAW_DESELECTED_AVOID) {
    printf ("(Avoid Dmin) ");
        }
        if (deselect & LAW_DESELECTED_DMIN) {
    printf ("(Between Dmin)");
        if (deselect & LAW_DESELECTED_DUPLICATE) { printf ("(Duplicated Code) "):
        if (deselect & LAW_DESELECTED_POWER) {
    printf ("(Power Limit) ");
        printf("\n");
```

```
//#define DO_FEW
  //#define DO_PRINT_0
//#define DO_PRINT_1
//#define DO_PRINT_2
//#define DO_PRINT_3
//#define DO_PRINT_5
  #ifdef DO_FEW
#define MAX_ATTN 1
#define MAX_DMIN 4
 #define START_DMIN_48
#define STEP_DMIN_4
 #define START_ATTN 11.0 #define STEP_ATTN 10
  #clse /* DO_FEW */
#define MAX_ATTN 14
#define MAX_DMIN 36
 #define START_DMIN 4
#define STEP_DMIN 4
 #define START_ATTN_0.0 #define STEP_ATTN_1.0 #endif /* DO_FEW */
 void
 main (void)
            sint15 idx, count;
           float attn.
sint15 bits_per_frame;
sint31 bit_rate, overall_bit_rate;
           \begin{array}{ll} \text{float input\_attn.} \\ \text{sint15 input\_tx\_dmin.} \\ \end{array}
           sint15 i, j, results lidx.
           struct results_s {
    float attn:
        sint 15 dmin.
        sint31 bit_rate_simple;
        sint31 bit_rate_exclude;
        sint31 bit_rate_idistinguishable_tx_dmin.
        sint31 bit_rate_idistinguishable_tx_dmin.
} results [MAX_ATTN * MAX_DMIN];
           results idx = 0:
           :nput_attn = START_ATTN;
input_tx_dmin = 120;
input_rx_dmin = 120;
for (j = 0; j < MAX_DMIN, input_tx_dmin += STEP_DMIN, input_rx_dmin += STEP_DMIN, j++) {
           printf ("\n"),
           u_law_init (&u_law):
          u_law_range (&u_law, 30, 4000),
u_law_dmin (&u_law, input_tx_dmin);
u_law_power (&u_law, -12.0 /*-9.47981*/);
u_law_power (&u_law, -12.0);
//
//
```

```
u_law_bit_rate (&u_law);
                 printf ("%6.2f %3d %3d ". input_attn. input_tx_dmin, input_rx_dmin);
                printf ("tx power %3.2f rx power %3.2f count %d dmin %d dup %d bit rate %ld\n", printf ("tx pwr %3.2f rx pwr %3.2f cnt %2d dmin %3d dup %2d rate %ld\n", u_law.tx_power_db, u_law.rx_power_db, u_law.count, u_law.dmin, u_law.indistinguishable, u_law.bit_ rate);
  11
 #endif
  u law_attenuate (&u_law_rx. input_attn);
u law_range (&u_law_rx. 22. 4000);
u law_dmin (&u_law_rx. input_rx_dmin);
u law_attenuate dmin (&u_law. &u_law_rx)
u law_exclude (&u_law_rx);
u law_discard_indinstinguishable (&u_law_rx);
u law_power (&u_law_rx, -12.0);
u law_discard_indinstinguishable (&u_law_rx);
u law_count_indinstinguishable (&u_law_rx);
u law_bit_rafe (&u_law_rx);
 1!
                                                                                                         /* transfer from transmitter */
                printf ("%6 2f %3d %3d ", input_attn, input_tx_dmin, input_rx_dmin);
               printf ("tx power %3 2f rx power %3.2f count %d dmin %d dup %d bit rate %ld\n", printf ("tx pwr %3.2f rx pwr %3.2f cnt %2d dmin %3d dup %2d rate %ld\n", u_law_rx tx_power_db, u_law_rx.rx_power_db, u_law_rx count, u_law_rx.dmin, u_law_rx.indisfinguishable, u_law_rx.bit_rate);
 11
attn = u_law_detect_attenuation (&u_law_rx).printf ("altenuation detected %f\n", altn):
 #endif
               results[results_idx] attn = input_attn:
results[results_idx].dmin = input_tx_dmin:
if (u_law_rx_dmin == 0) {
                              results[results_idx] bit_rate_simple = 0;
                élse {
                              results[results_idx].bit_rate_simple = u_law_rx.bit_rate;
               }
u_law_attenuate (&u_law_rx, input_attn);
u_law_range (&u_law_rx, 22, 4000);
u_law_dmin (&u_law_rx, input_rx_dmin);
u_law_attenuate dmin (&u_law, &u_law_rx);
u_law_exclude (&u_law_rx);
u_law_discard_indinstinguishable (&u_law_rx);
u_law_power (&u_law_rx, -12.0);
u_law_discard_indinstinguishable (&u_law_rx);
u_law_count_indinstinguishable (&u_law_rx);
u_law_bit_rate (&u_law_rx);
                                                                                                       /* transfer from transmitter */
//
               printf ("%6.2f %3d %3d ", input_attn, input_tx_dmin, input_rx_dmin);
              printf ("tx power %3.2f rx power %3.2f count %d dmin %d dup %d bit rate %ld\n", printf ("tx pwr %3.2f rx pwr %3.2f cnt %2d dmin %3d dup %2d rate %ld\n", u_law_rx.tx_power_db, u_law_rx.rx_power_db, u_law_rx.count, u_law_rx.dmin, u_law_rx indistinguishable, u_law_rx.bit_rate);
#ifdef DO PRINT_2
```

```
}
               attn = u_law_detect_attenuation (&u_law_rx);
printf ("attenuation detected %f\n", attn);
  #endif
               if (u_law_rx.dmin == 0) {
    results[results_idx].bit_rate_exclude = 0;
               else (
                            results[results_idx].bit_rate_exclude = u_law_rx.bit_rate;
               }
  u law attenuate (&u_law_rx. input_attn);
u law_range (&u_law_rx. 22, 4000);
u law_dmin (&u_law_rx. input_rx_dmin);
u law_attenuate_dmin (&u_law_&u_law_rx);
u law_discard_indinstinguishable (&u_law_rx);
u law_power (&u_law_rx, -12.0);
u law_power (&u_law_rx, (-12.0 - attn));
u law_count_indinstinguishable (&u_law_rx);
u_law_bit_rate (&u_law_rx);
  11
               printf ("%6.2f %3d %3d ", input_attn, input_tx_dmin, input_rx_dmin);
              printf ("tx power %3 2f rx power %3 2f count %d dmin %d dup %d bit rate %ld\n", printf ("tx pwr %3.2f rx pwr %3 2f cnt %2d dmin %3d dup %2d rate %ld\n", u_law_rx.tx_power_db, u_law_rx.rx_power_db, u_law_rx.count, u_law_rx.dmin, u_law_rx.indistinguishable, u_law_rx.bit_rate);
  //
attn = u_law_detect_attenuation (&u_law_rx);
printf ("altenuation detected_%f\n", altn);
 #endif
              results[results_idx] bit_rate_distinguishable_tx_dmin = u_law_rx.bit_rate.
 u_law_attenuate (&u_law_rx, input_attn);
u_law_range (&u_law_rx, 22, 4000);
u_law_dmin (&u_law_rx, input_rx_dmin);
u_law_attenuate_dmin (&u_law_&u_law_rx);
u_law_discard_indinstinguishable (&u_law_rx);
u_law_power (&u_law_rx, -12.0);
u_law_power (&u_law_rx, (-12.0 - attn));
u_law_count_indinstinguishable (&u_law_rx),
u_law_bit_rafe (&u_law_rx);
 //
 //
 //
              printf ("%6 2f %3d %3d ", input_attn, input_tx_dmin, input_rx_dmin);
             printf ("tx power %3.2f rx power %3.2f count %d dmin %d dup %d bit rate %ld\n", printf ("tx pwr %3.2f rx pwr %3.2f cnt %2d dmin %3d dup %2d rate %ld\n", u_law_rx tx_power_db, u_law_rx.rx_power_db, u_law_rx.count, u_law_rx.dmin, u_law_rx.indistinguishable, u_law_rx.bit_rate);
//
attn = u_law_detect_attenuation (&u_law_rx); printf ("altenuation detected %f\n", altn);
#endif
```

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```
results[results_idx++].bit_rate_distinguishable_rx_dmin = u_law_rx.bit_rate;
 bits_per_frame = u_law_map_symbol_set (&u_law_rx, &u_law_rx);
        bit_rate = (sint31) (((float) (bits_per_frame) / 6.0 + 1.0) * 8000.0);
 #ifdef USE_4D_TRELLIS overall_bit_rate = (sint31) (((float) (bits_per_frame) / 6.0 + 1.0 + 0.5) * 8000.0):
 #else
        overall_bit_rate = (sint31) (((float) (bits_per_frame) / 6.0 + 1.0) * 8000 0):
 #endif
 #ildef DO PRINT 5
        printf ("bits per frame %d bit rate %ld overall bit rate %ld (with trellis)\n", bits_per_frame, bit_rate, overall_bit_rate);
 #endif
 #if O
        #endif
            #ifndef DO_FEW
for (idx = 0; idx < MAX_ATTN * MAX_DMIN; idx++) {
    printf("%6.2f %3d %5ld %5ld %5ld\n", results[idx].attn, results[idx].dmin.
    results[idx] bit_rate_simple. results[idx].bit_rate_exclude.
    results[idx] bit_rate_distinguishable_tx_dmin,
    results[idx].bit_rate_distinguishable_rx_dmin);
}
```

```
····
          pcmcnv.c
          (C) 1997 VoCAL Technologies Ltd.
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          VoCAL Technologies Ltd.
          3032 Scott Blvd.
Santa Clara, CA 95054
          Product:
                            C
          Module:
                                     PCM
          This file contains the PCM conversion functions.
          Revision Number:
Revision Status
                                     $RevisionS
                                     $State$
$Date$
          Last Modified:
          Identification:
          Revision History: $Log$
Revision 1.0 1997/03/01 00:00:00 VD
Initial release of software
 #include "standard.h"
#include "pcm.h"
 #include <stdio.h>
 sint15
u_law_pcm_encode (sfract15 input)
         sfract15 value, seg;
         value = input;
if (input < 0) value = -input;</pre>
                                                                /* Take absolute value */
         value = value + 33;
if (value > 8159) value = 8159;
                                                                /* Limit values */
seg = iexp (value);
//printf("%5d %5d %5d", input, value, seg);
value = norm (value, seg);
                                                                /* Compute exponent */
                                                       /* Normalize value */
value = value ^ 0x4000;
value = value >> 10;
//printf(" %5d", value);
                                                       /* Clear bit */
/* Position bits */
         /* Insert sign bit */
         seg = seg + 9;
seg = seg << 4;
                                                                /* Compute segment */
value = value | seg;
//printf(" %04x", value);
                                                       /* Insert segment bits */
value = value ^ 0x00ff;
//printf(" %5d\n", value);
    return (sint15) value;
                                                       /* Invert bits */
}
#ifdef DO_U_LAW
                                                       /* Input sample passed in AR (1.15) */
/* Take absolute value */
/* 33 << 2 */
                           AR = ABS AR;
                           AY0 = 132;
AR = AR + AY0;
SR1 = 32636;
IF AV AR = PASS SR1;
SE = EXP AR (HI);
                                                                /* Limit values */
                                                                /* Compute exponent */
```

```
SR = NORM AR (LO); /* Normalize value
AY0 = 0x4000;
AR = SR0 XOR AY0; /* Clear bit */
SR = LSHIFT AR BY -10 (LO); /* Position bits */
AX0 = SF. AR = PASS AY0;
IF POS AR = PASS 0; /* Create sign bit
SR = SR OR LSHIFT AR BY -7 (LO); /* Insert s
AY0 = 7: /* 9 if usit
                                                                                   /* Normalize value */
                                                                                   /* Create sign bit */
(LO): /* Insert sign bit */
/* 9 if using 8031 range */
/* Compute segment */
(LO): /* Insert segment bits */
                                    AY0 = 7;

AR = AX0 + AY0.

SR = SR OR LSHIFT AR BY 4 (LO);

AY0 = 0xFF;

AR = SR0 XOR AY0; /* Inv
 X
                                                                                   /* Invert bits */
                                    RTS.
                                                                                               /* Pass on rate converted value *
 #endif
 sfract15
 u_law_pcm_decode (uint8 code)
             sfract15 value, seg:
             value = code & 0x00ff;
value = value ^ 0x00ff;
                                                                       /* Mask bits */
/* Invert bits */
            seg = value & 0x0070;
value = value ^ seg:
                                                                       /* Isolate segment bits */
                                                                       /* Remove segment bits */
/* Shift to low bits */
             seg = seg >> 4:
            /* Determine sign */
                                                                      /* Process negative value */
/* Add segment offset */
/* Position bits */
/* Remove segment offset */
                                                                      /* Process positive value */
/* Add segment offset */
/* Position bits */
/* Remove segment offset */
            else {
                        value = value + value + 33:
value = value << seg:
                        value = value - 33;
            }
            return value.
 sfract15
u_law_pcm_threshold (uint8 code)
            sfract15 value, seg.
            value = code & 0x00ff;
value = value ^ 0x00ff.
                                                                      /* Mask bits */
/* Invert bits */
                                                                      /* Isolate segment bits */
/* Remove segment bits */
/* Shift to low bits */
            seg = value & 0x0070:
            value = value & 0x000f;
            seg = seg >> 4;
seg++;
            value = value + 17;
value = value << seg.
value = value - 33;
                                                                      /* Add segment offset */
/* Position bits */
                                                                                  /* Remove segment offset */
                                                          /* Determine sign */
/* Process negative value */
            if ((code & 0x80) == 0) {
                        value = -value:
           return value.
#ifdef DO_A_LAW
a_law_pcm_encode:
                                                                                  /* Input sample passed in AR (1.15) */
                                   AR = ABS AR;
AY0 = 511; /* 127 */
AF = AR - AY0;
                                                                                  /* Take absolute value */
                                                                                  /* Check for zero segment */
                                   IF GT JUMP a_law_pcm_enc_1;
```

```
SR = LSHIFT AR BY -4 (LO). /* Downshift bits */
AR = 0x4000:
IF NEG AR = PASS 0: /* Create sign bit */
SR = SR OR LSHIFT AR BY -7 (LO); /* Insert sign bit */
AY0 = 0x55:
                                                    AR = SRO XOR AYO:
RTS:
                                                                                                                        /* Invert bits */
                                                                                                                                          /* Pass on rate converted value */
 a_law_pcm_enc_1:
                                                    SE = EXP AR (HI). /*
AX0 = SE, SR = NORM AR (LO):
AY0 = 0x4000;
                                                                                                                         /* Compute exponent */
): /* Normalize value */
                                                    AR = SR0 XOR AY0: /* Clear bit */
SR = LSHIFT AR BY -10 (LO): /* Position bits */
AR = PASS AY0:
IF NEG AR = PASS 0: /* Create sign bit
                                                    IF NEG AR = PASS 0; /* Create sign bit */
SR = SR OR LSHIFT AR BY -7 (LO); /* Insert sign bit */
AY0 = 7;
                                                    AR = AX0 + AY0;
If I I AR = PASS 0:
SR = SR OR LSHIFT AR BY 4 (LO);
AY0 = 0x55:

/* Compute segment */
Insert segment bits */
                                                    AR = SR0 XOR AY0;
                                                                                                                        /* Invert bits */
                                                    RTS:
                                                                                                                                         /* Pass on rate converted value */
                                                    ident(IDENT_RX_B1_PCM_DECODE):
                                                                                                                        a_law_pcm_decode:
                                                    AY0 = 0x55
                                                    AR = AR XOR AY0: /* Invert bits */
SR1 = 0x8; /* Set sign bit */
SR0 = 0x800; /* Set LSB of interval */
SR = SR OR LSHIFT AR BY -12 (LO): /* Isolate segment and interval */
                                                  AY0 = 32;
AX0 = AR, AF = PASS AY0:
AY0 = 9;
AR = SR1 - AY0;
IF LT AF = PASS 0;
IF EQ AR = PASS 0;
IF EQ AR = PASS 0;
IF EQ AR = PASS 0;
IF SR = LSHIFT SR0 BY -11 (LO);
IF solate interval */
SR = LSHIFT AR (LO);
IF Position output */
SR = LSHIFT SR0 BY 3 (LO);
AY0 = 0xFF80;
AR = SR0, AF = AX0 + AY0;
IF LT AR = - SR0;
IF LT AR = - SR0;
IF it is, negate result */
RTS:
IF Segment bias */
IF Segment bias */
IF Segment bias */
IF Check if sign bit set */
IF it is, negate result */
IF Pass on rate cor
                                                                                                                                         /* Segment bias */
/* Determine shift */
                                                                                                                       /* Check if sign bit set */
/* If it is, negate result */
/* Pass on rate converted value (1.15) */
                                                   RTS:
#endif /* DO_A_LAW */
```

```
math.c
     (C) 1997 VoCAL Technologies Ltd.
     ALL RIGHTS RESERVED. PROPRIETARY AND CONFIDENTIAL
      VoCAL Technologies Ltd.
     3032 Scott Blvd.
Santa Clara, CA 95054
     Product.
                  C
     Module.
                  MATH
     This file contains fractional math support functions
                       $Revision$
$State$
$Date$
$Id$
     Revision Number 
Revision Status
      Last Modified
     Identification:
     Revision History. $Log$
Revision 1.0 1997/03/01 00.00:00 VD
Initial release of software
#include "standard h"
#include "pcm.h"
#include <math.h>
 sint15
jexp (sfract15 value)
     sint15 exp.
     if (value < 0) {
    value = -value:
     exp = 15:
     if (value == 0) {
          return exp;
     while ((value & 0x4000) == 0) {
          --èxp:
         value = value << 1;
     return exp
}
norm (sfract15 value, sint15 exp)
    return (value << -exp):
float
db_to_float (float db)
    float db_float:
    db_float = db / 20.0;
db_float = pow (10.0, db_float);
    return db_float;
```

```
float
   db_to_power (float db)
                  float db_float;
                  db_float = db / 10.0;
db_float = pow (10.0, db_float);
                  return db_float:
         float_to_db (float power)
                  float float_db.
                  float_db = log10 (power) * 20 0:
                  return float_db:
 }
 power_to_db (float power)
                  float power_db:
                  power_db = log10 (power) * 10.0;
                  return power_db;
 }
 uint48_add (uint48 *src1, uint48 *src2, uint48 *dst)
                  uint 16 s1f. s1m. s1h. s2f. s2m. s2h, dstf. dstm, dsth.
                  s11 = src1 -> lsw;
                 s1m = src1->mid,
s1h = src1 >msw;
                s2l = src2->lsw;
s2m = src2 >mid;
s2h = src2->msw;
                asm {
                                  mov ax. s1l
                                 add ax. s2l;
mov dstl. ax:
                                  mov ax, s1m;
                                 adc ax. s2m.
mov dstm. ax;
                                 mov ax. s1h:
adc ax. s2h;
mov dsth. ax,
                dst->Isw = dstl:
                dst->mid = dstm.
                dst->msw = dsth:
                 printf("\%04x \ \%04x \ \%04x = \ \%04x \ \%04x \ \%04x + \ \%04x \ \%
//
}
```

void

```
uint48_sub (uint48 *src1, uint48 *src2, uint48 *dst) {
      uint16 s1l, s1m, s1h, s2l, s2m, s2h, dstl, dstm, dsth;
      s1l = src1->lsw;
s1m = src1->mid,
s1h = src1->msw;
      s2l = src2->lsw;
s2m = src2->mid,
s2h = src2->msw;
      asm {
mov ax s1l;
sub ax, s2l;
mov dsll, ax;
            mov ax, s1m;
sbb ax, s2m;
mov dstm, ax;
            mov ax, s1h;
sbb ax, s2h;
mov ds1h, ax;
      }
      dst->lsw = dstl;
dst->mid = dstm;
dst->msw = dsth;
}
sfract15
fmpy (sfract15 a, sfract15 b)
      long a_long, b_long; short a_short;
      a_long = a;
b_long = b;
     a_long = a_long * b_long;
a_short = (short) (a_long >> 15);
      return a_short:
```

```
pcm.h
          (C) 1997 VoCAL Technologies Ltd.
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          VoCAL Technologies Ltd.
3032 Scott Blvd
Santa Clara, CA 95054
          Product:
                             C
          Module:
                                      PCM
          This file defines the PCM utility functions.
         Revision Number
Revision Status
Last Modified.
Identification:
                                      $Revision$
                                      $State$
$Date$
                                      $Id$
          Revision History:
                                      $Log$
        ·····
#ifndef PCM PCM H
#define PCM PCM H
typedef struct {
uint16 lsw;
uint16 mid;
         uint16 msw:
} uint48;
sint15 fexp (sfract15 value),
sint15 norm (sfract15 value, sint15 exp);
float db_to_float (float db);
float db_to_power (float db);
float float_fo_db (float power);
float power_fo_db (float power);
void uint48_add (uint48 *src1, uint48 *src2, uint48 *dst); void uint48_sub (uint48 *src1, uint48 *src2, uint48 *dst);
sint 15 u_law_pcm_encode (sfract 15 input):
sfract 15 u_law_pcm_decode (uint8 code);
sfract 15 u_law_pcm_threshold (uint8 code);
#endif /* _PCM_PCM_H */
```

```
standard.h
         (C) 1994, 1995, 1996 VoCAL Technologies Ltd.
         ALL RIGHTS RESERVED. PROPRIETARY AND CONFIDENTIAL.
         VoCAL Technologies Ltd.
         3032 Scott Blvd
Santa Clara, CA 95054
         Product:
                         MODEM 101
         Module:
                                 SYSTEM
         This file defines the standard system definitions.
         Revision Number
                                  $Revision$
         Revision Status:
                                  $State$
         Last Modified:
                                  $Date$
         Identification:
                                  $1d$
         Revision History:
                                 $Log$
  #ifndef_SYSTEM_STANDARD_H
#define_SYSTEM_STANDARD_H
#ifdef DO_CX025
#include <GLBL_Globals h>
#include <m68EC040.h>
#endif /* DO_CX025 */
#ifdef DO_WIN
/*-#include < null.h>-*/
#define STDC FA
//#include <stddef.h>
                    FALSE
#define strupr(a) _strupr(a)
#define strlwr(a) _strlwr(a)
#define inp(a) _inp(a)
#define inpw(a) _inpw(a)
#define outp(a.b) _outp(a.b)
#define outpw(a.b) _outpw(a.b)
#define near
#define NULL ((void *)0)
#endif /* DO_WIN32 */
#else /* DO_WIN */
#ifndef DO_CX018_A
/*#include < null.h>*7
#ifndef NULE
#if defined(__TINY__) || defined(__SMALL__) || defined(__MEDIUM__)
#define NUTL_0
#else
#define NULL OL
#endif
#endif
#endif /* DO_CX018__A */
#endif /* DO_WIN */
```

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```
typedef unsigned char uint8; /* range 0-255 */
typedef unsigned char umod8; /* 8 bit math requirements */
typedef unsigned char octet; /* octet data */
#idef DO FORCED_BYTE_ALIGNED */
typedef unsigned char octet: /* octet data */
#idef DO FORCED_BYTE_ALIGNED
typedef unsigned short pack8:
#else /* DO FORCED_BYTE_ALIGNED */
typedef unsigned char pack8. /* packed octet data */
#endif /* DO FORCED_BYTE_ALIGNED */
typedef pack8 expand8: /* expand cctet data to uint16 */
typedef signed char sint7:
typedef unsigned short uint16: typedef signed short sint15, typedef signed short sfract15.
 typedef unsigned long uint32.
 typedef signed long sint31.
 #ifdef DO_CX025
 #define far
#define interrupt
#endif /* DO_CX025 */
 /· *^^----
#define MAX_UINT8 (255)
#define MAX_SINT7 (127)
#define MIN_SINT7 (128)
#define MAX_UINT16 (65535)
#define MAX_SINT15 (32767)
#define MIN_SINT15 (-32768)
#define MAX_UINT32 (4294967296)
#define MAX_SINT31 (2147483647)
#define MIN_SINT31 (-2147483648)
#define MIN_DOUBLE (1.7e-308)
#define MAX_DOUBLE (1.7e308)
typedef uint8 byte;
typedef uint 16 word;
typedef int bool;
#ifndef DO_CX025
#define FALSE 0
#define TRUE (!FALSE)
#endif /* DO_CX025 */
#if defined(DO_ADI2181) || defined(DO_ISAR) typedef uint32 dsp_pm_t: /* Of size of DSP program memory contents typedef uint16 dsp_dm_t; /* Of size of DSP data memory contents typedef uint16 dsp_addr_t: /* Of size of DSP addresses typedef uint16 dsp_xddr_t: /* Of size of extended DSP addresses #endif /* DO_ADI2181 || DO_ISAR */
                                                                                                                                             •1
#define forever for (::)
#ifdef DO CX025
#else /* DO_CX025 */
#ifdef DO CX018
#IIDET DO CXUT8 A
#define interrupt disable_onto_stack() \
    {asm(" ORI #$700,SR\n NOP\n NOP\n");}
#define interrupt_restore_from_stack() \
    {asm(" ANDI #$f8ff.SR\n NOP\n NOP\n");}
#else /* DO_CX018__A */
#ifdef DO WIN
#define interrupt_disable_onto_stack()
```

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*/

```
#define interrupt_restore_from_stack()
#else /* DO_WIN */
#define interrupt_disable_onto_stack() {asm pushf;asm cli;}
#define interrupt_restore_from_stack() {asm popf;}
#endif /* DO_WIN */
   #endif /* DO_CX018__A */
#endif /* DO_CX025 *7
   #ifdef DO_CAPI20
#define DEBLEVEL
   #pragma code_seg("_LTEXT", "LCODE")
#include <debtig.h>
   #include <vxdwraps.h>
  #else /* DO_CAPI20 */
#ifdef DO_ISAR
typedef const char far* LPCSTR:
typedef char far* LPSTR;
#define PASCAL pascal
#endif /* DO_ISAR */
#endif /* DO_CAPI20 */
  #ifdef DO_WIN32
//#define sprintf Sprintf
#endif /* DO_WIN32 */
/*
  /
/-
/-
  #define print_debug_off(A)
#define print_diag_off(A)
 #ifndef DO_CAPI20
#define print_primary(A) print_routine A
#define print_std(A) print_routine A
#define print_info(A) print_routine A
#define print_diag_on(A) print_routine A
#define print_debug_on(A) print_routine A
#define print_debug_on(A) print_routine A
#define report_anomaly(A) report_anomaly_routine (A)
#else /* DO_CAPI20 */
 #define print_std(A) Debug_Printf A
#define print_info(A) Debug_Printf A
#define print_diag_on(A) Debug_Printf A
#define print_debug_on(A) Debug_Printf A
#define report_anomaly(A) report_anomaly_routine (A)
  #endif /* DO_CAPI20 */
#ifdef DO_PRINTS_DISABLED
#undef print_primary
#undef print_std
#undef print_info
#undef print_debug
#undef report_anomaly
#define print_std(A)
#define print_std(A)
#define print_info(A)
#define print_debug(A)
#define report_anomaly(A)
#endif /* DO_PRINTS_DISABLED */
 #ifdef DO PRINTS DISABLED
#ifdef DO_CX025
#undef print_primary(A)
#undef print_std(A)
#undef print_info(A)
#undef print_debug(A)
#undef report_anomaly(A)
#endif /* DO_CX025 */
#endif /* SYSTEM_STANDARD_H */
```

Ø